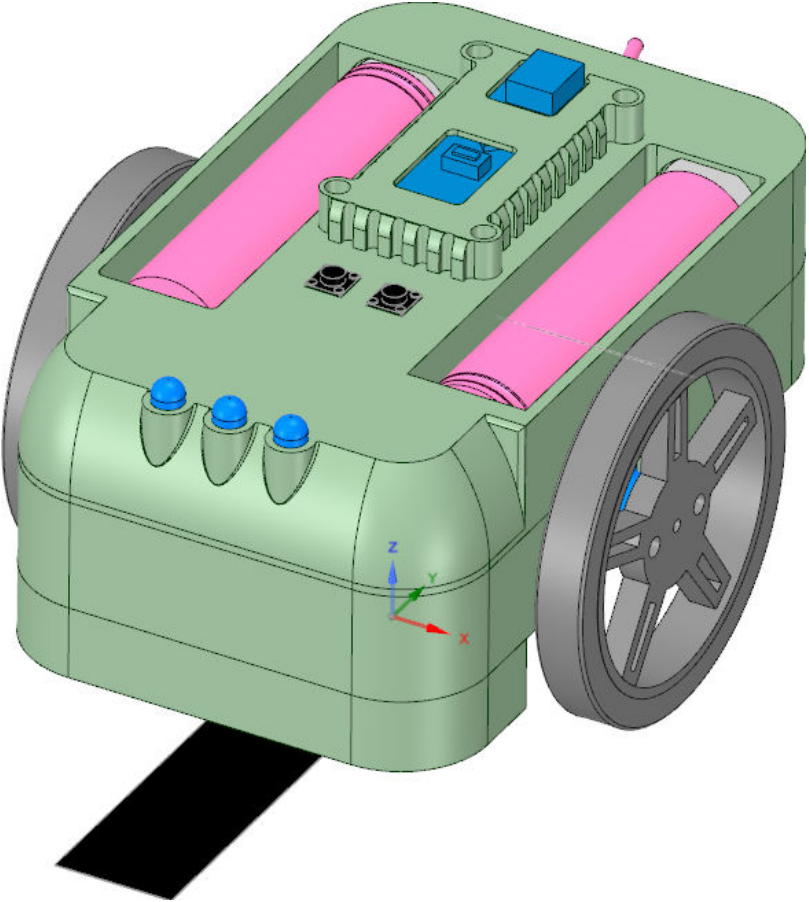
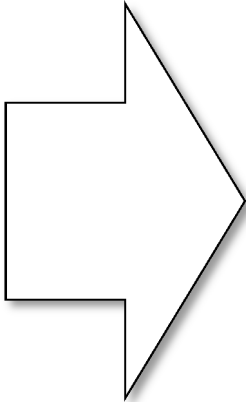
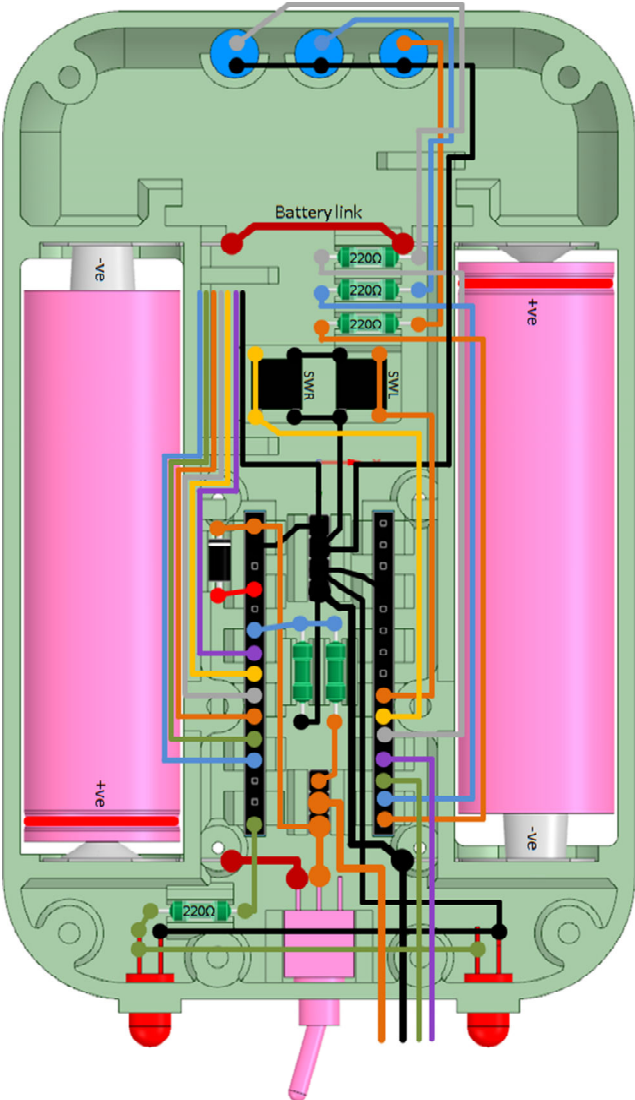


TrackBot v2

Circuits & Wiring



Hand Tools:

Fine Nosed Pliers
Side Cutters
M3 Tap
M4 Tap
2.5 mm Drill
3.0 mm Drill
3.5mm Drill
6.0 mm Drill
Needle Files
M3 Box Spanner
Screwdriver
Craft Knife



Note: Not all items
are shown here.

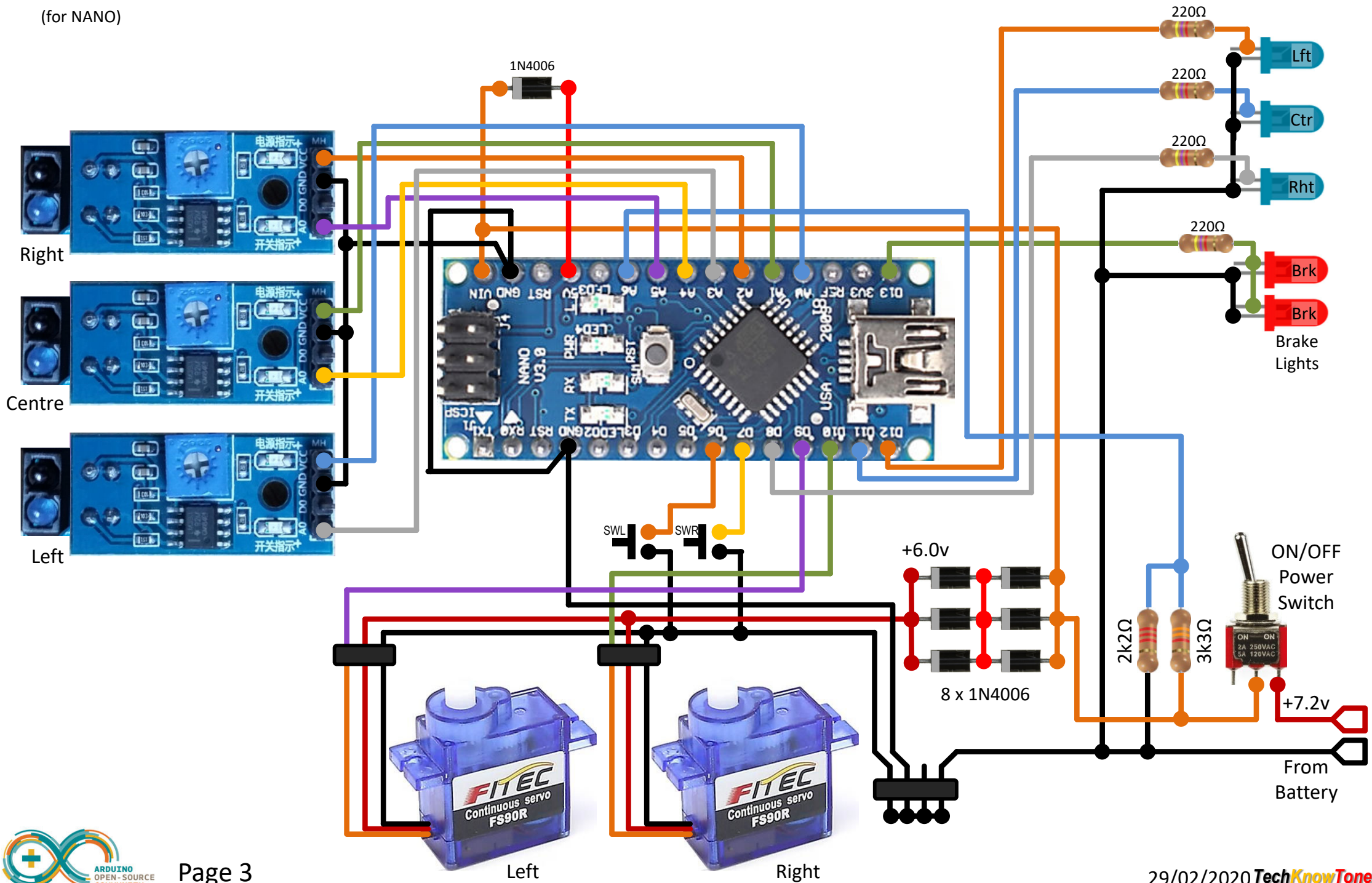
Hand Tools:

- Temperature controlled iron
- Heat shrink sleeving gun
- Hot melt glue gun
- Solder flux
- Resin cored solder
- 6mm adhesive copper tape
- Screw drivers
- Wire wrapping tool
- Wire wrapping wire 30 AWG



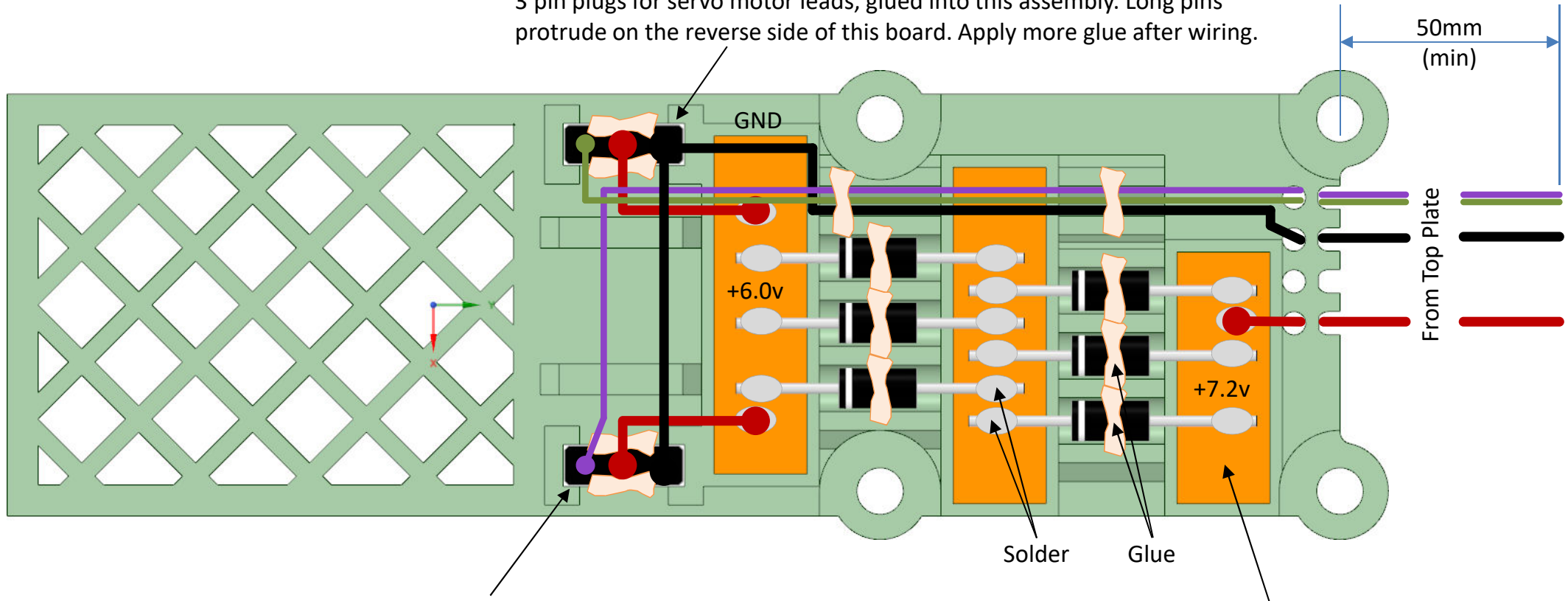
TrackBot v2 Circuit

(for NANO)



TrackBot v2 – Diode Board Wiring

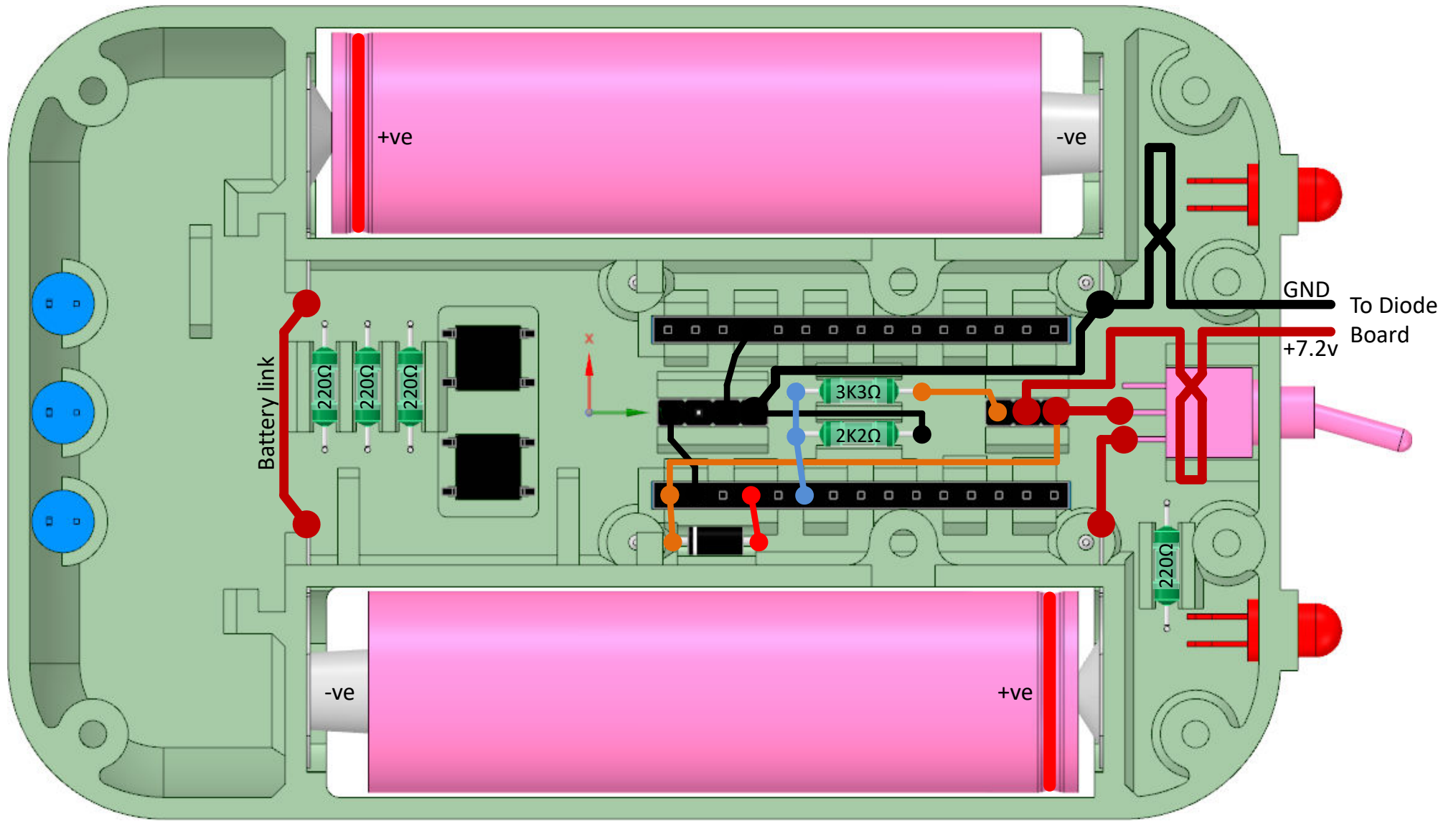
3 pin plugs for servo motor leads, glued into this assembly. Long pins protrude on the reverse side of this board. Apply more glue after wiring.



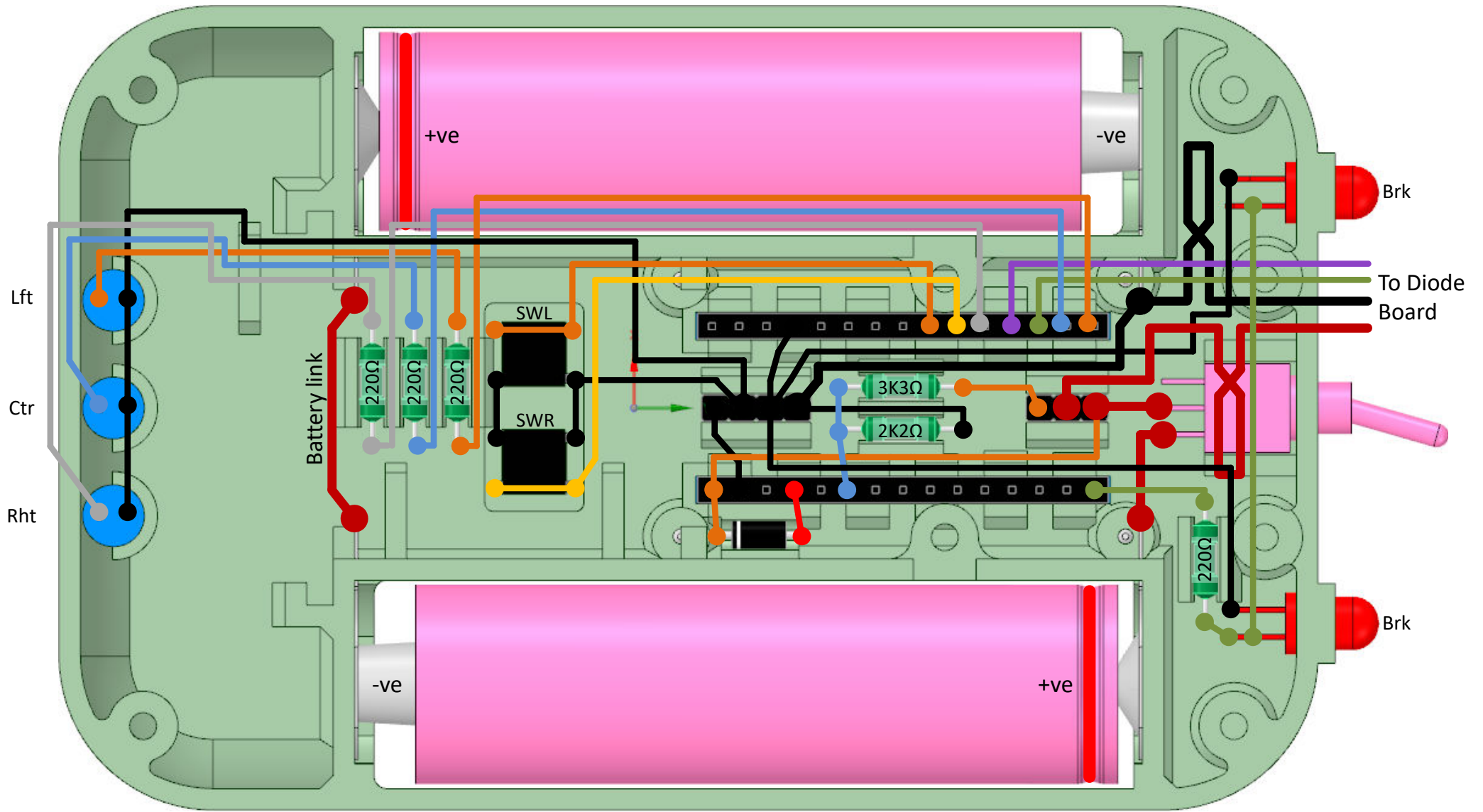
Note:
PWM connections are wire-wrapped, then tested, then soldered if successful.
4 layers of copper foil tape improves thermal conduction during soldering of IN4006 diodes.

4 layers of 6mm adhesive copper foil tape

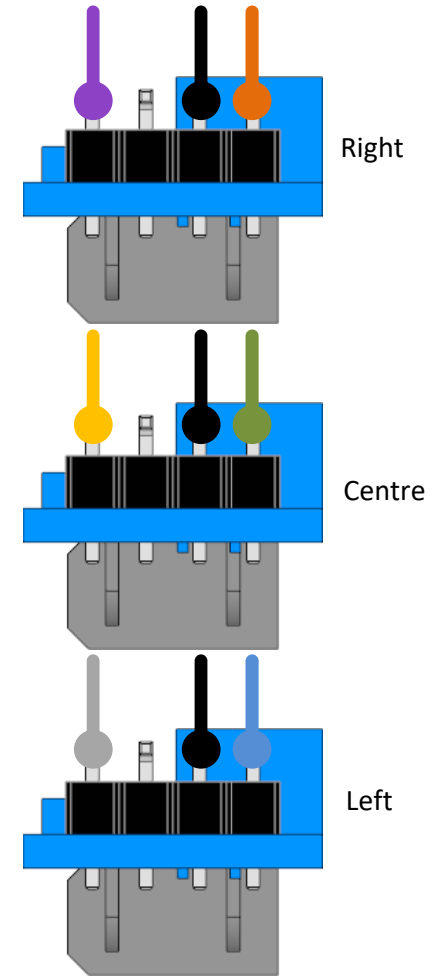
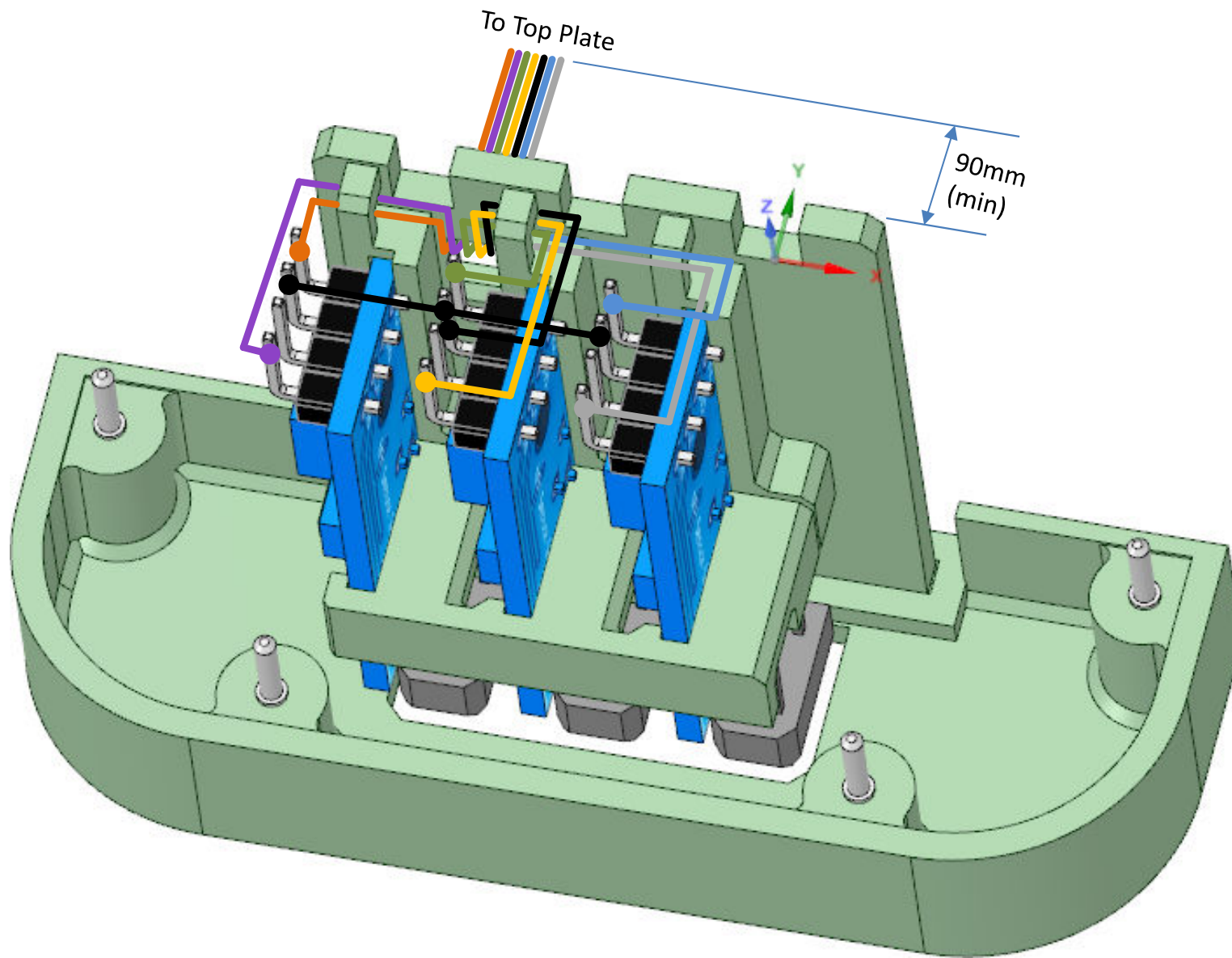
TrackBot v2 – Top Plate ‘Power’ Wiring



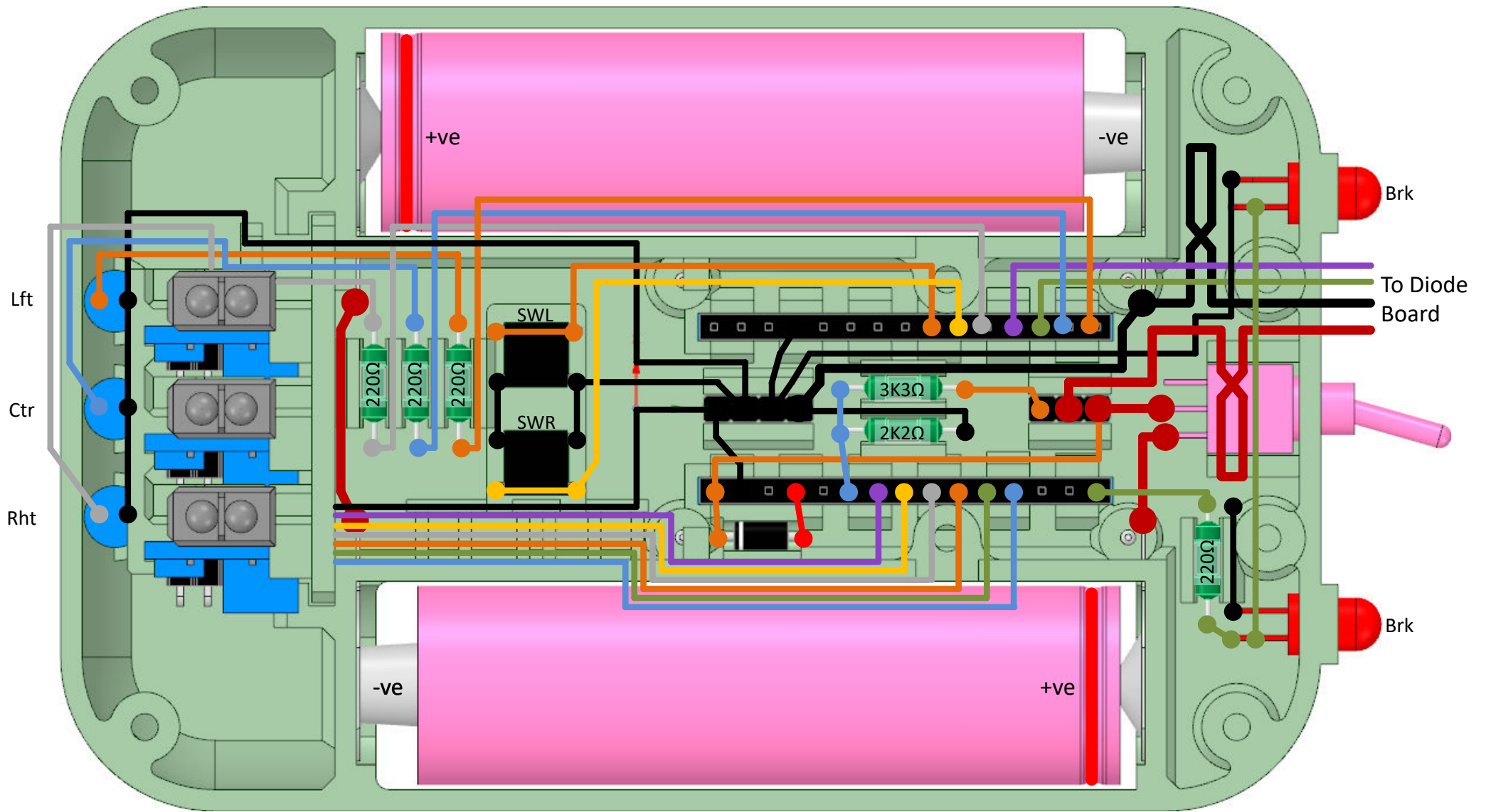
TrackBot v2 – Top Plate 'LED & Switches' Wiring



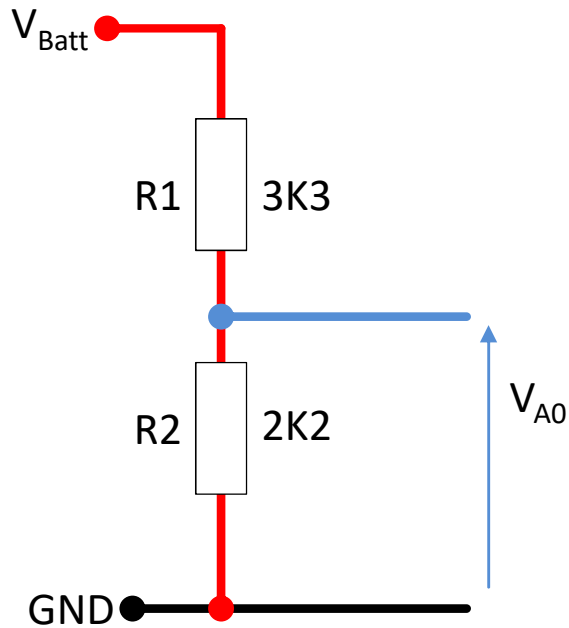
TrackBot v2 – Sensor Plate Wiring



TrackBot v2 – Top Plate ‘Sensor’ Wiring



Battery Monitor (Protection)



$$V_{A0} = \frac{V_{Batt} \times R2}{R1 + R2}$$

$$V_{A0} = \frac{V_{Batt} \times 2K2}{5K5}$$

$$V_{FSD} = 12.5v @ V_{A0} = 5v$$

$$V_{A0D} = \frac{V_{A0} \times 1023}{5} \quad \text{voltage read by 10-bit ADC}$$

$$V_{A0D} = \frac{V_{Batt} \times 0.4 \times 1023}{5}$$

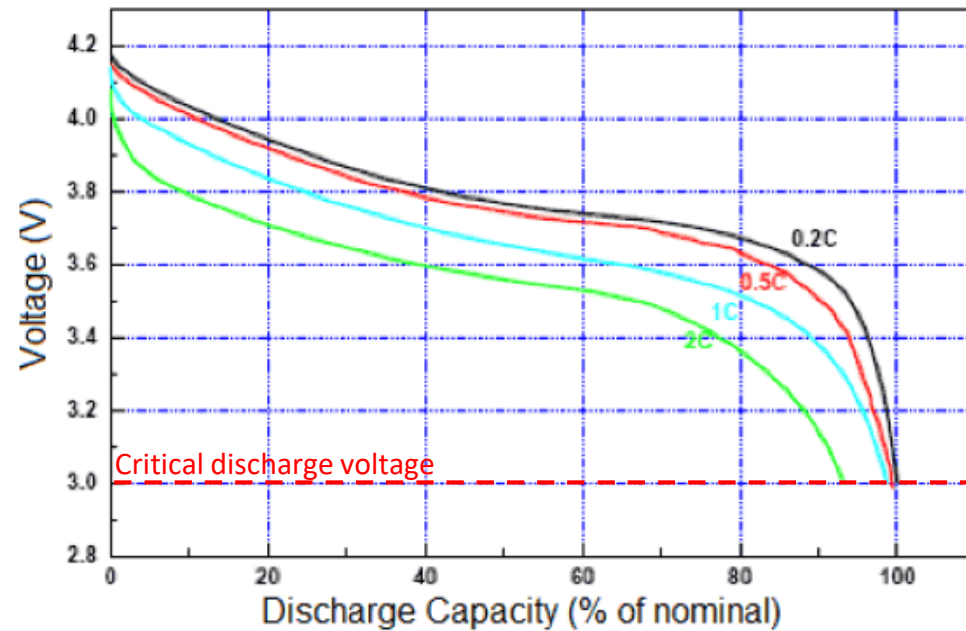
Two cells in series gives a nominal 7.4v constant discharge voltage. To prevent damage, stop using once the following conditions are reached:

- 3.60 + 3.00 = 6.60v (one battery fades early)
- 3.30 + 3.30 = 6.60v (both batteries fade together)

Hence $V_{A0D} = 540 @ V_{Batt} = 6.60v$

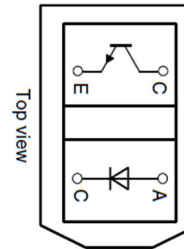
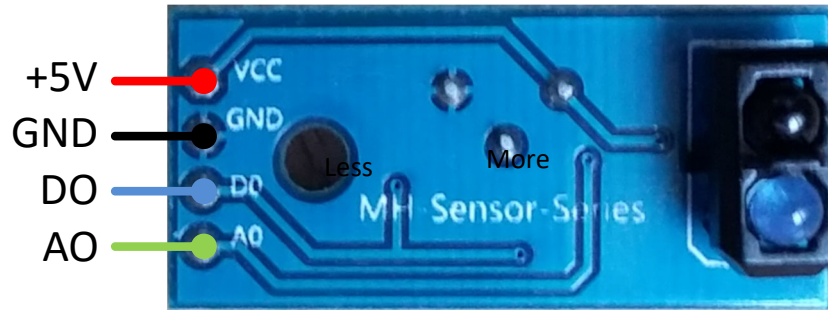
The code will shut down when the value drops to 540.

18650 Lithium Battery Discharge Profile

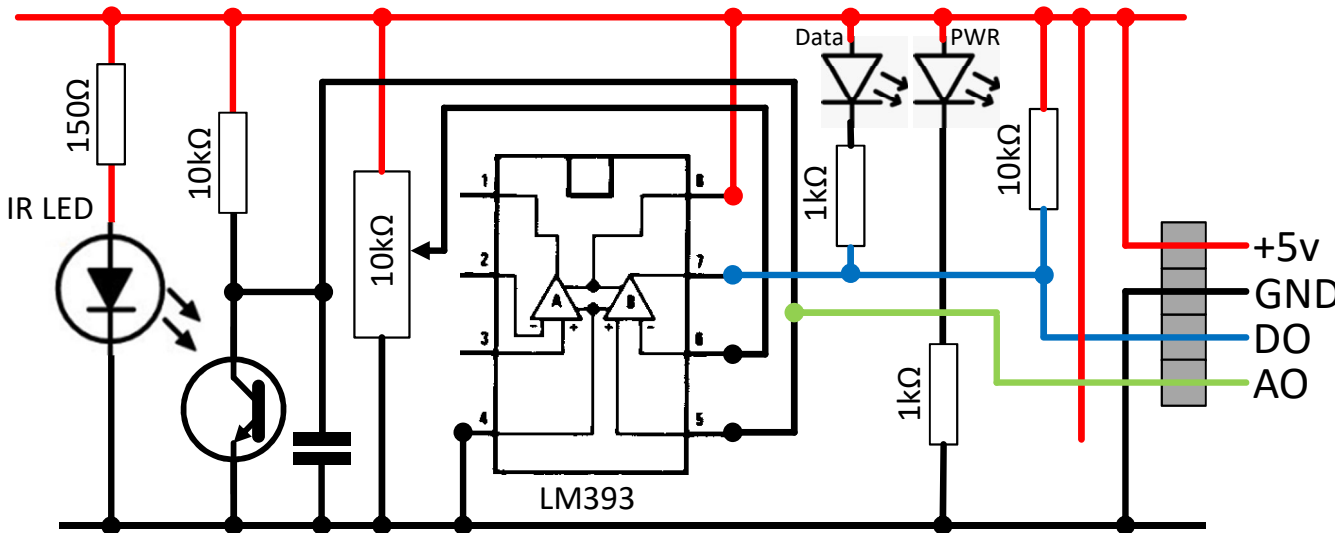
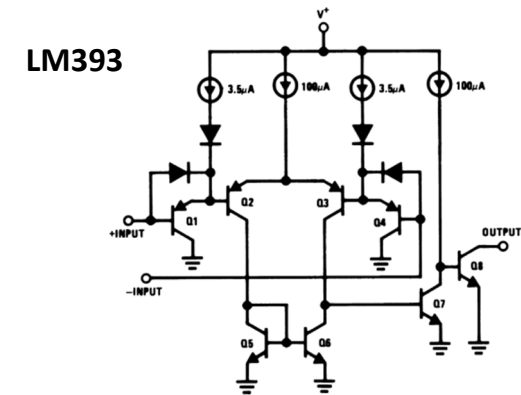
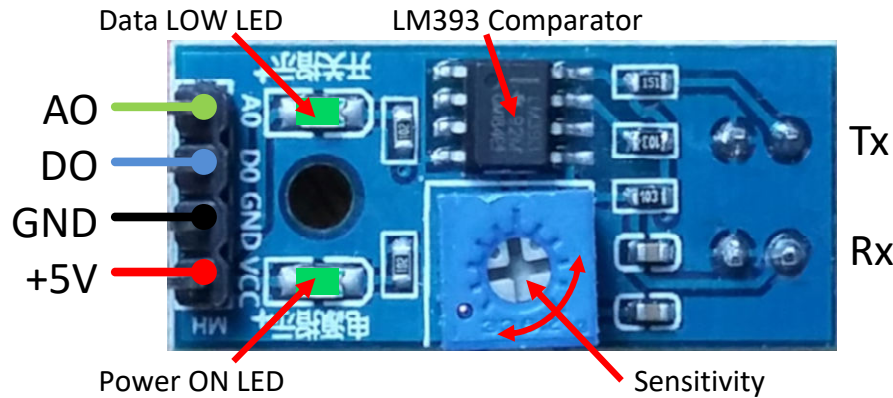


Discharge: 3.0V cutoff at room temperature.

IR Obstacle Sensor



Proximity	LED	Output
Close	ON	LOW
Far	OFF	HIGH



LM393 is open collector output, therefore several devices can be connected to a common active LOW data line. LM393 has a minimum sink current of 6mA, typical 16mA. As each 'Data' LED draws ~2.5mA, you could connect between 2 and 6 circuits together.

Pcb current = 30mA with both LEDs ON.